

# Fluid mechanics of lubrication I: fundamental aspects of a rigorous theory

Bernhard Scheichl

Institute of Fluid Mechanics and Heat Transfer



TECHNISCHE  
UNIVERSITÄT  
WIEN  
Vienna University of Technology

MINILUBES AC<sup>2</sup>Tion Day

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## Main objectives

- existing gap in tribological literature:  
lubrication represented 'unsatisfactorily accurate'  $\Rightarrow$
- describing lube flows by adopting first principles of continuum mechanics:  
asymptotic theory of hydromechanical lubrication

Why is this expedient?

- rational estimate of methodical error
- rational extension of classical theory to include e.g.  
EHD, inertia, micro-scale effects (cavitation, surface roughness)

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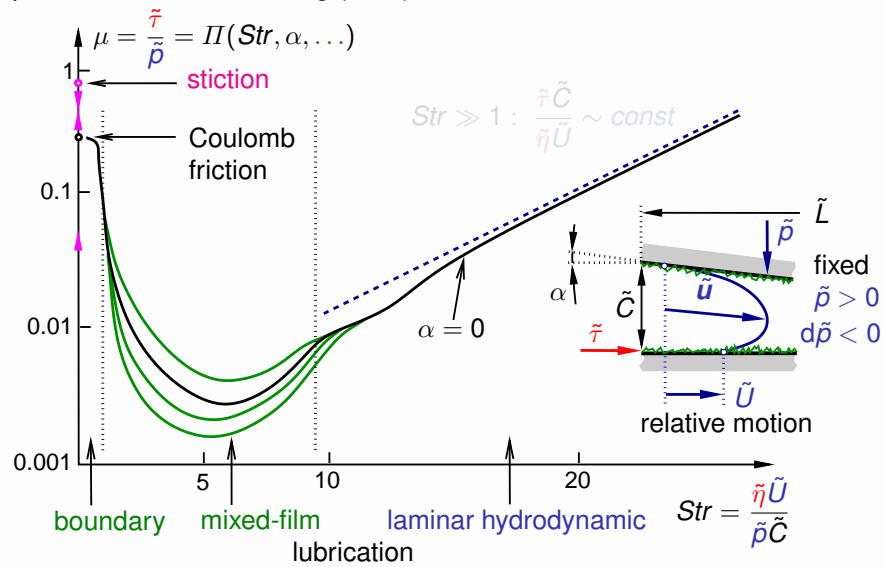
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# Overview

## Phenomenon of lubrication

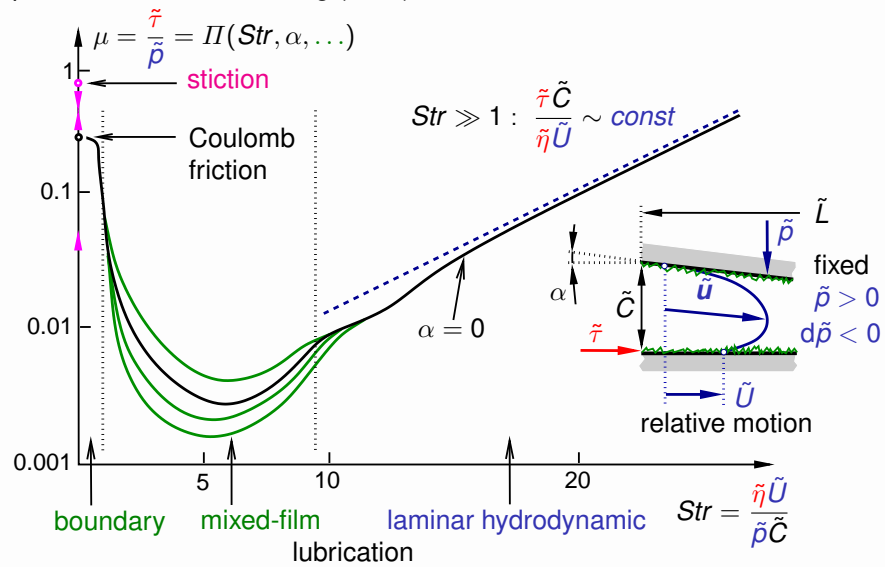
pressurised counter-sliding (tilted) solid contacts: Stribeck curve





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## Basic (realistic) assumptions

### lubricant flow

- 'simple' fluid
  - excludes multi-phase flow (binary mixture lubricant–air):  
2 (intensive) state variables define local thermodynamic equilibrium
- Newtonian fluid
  - lube oils, ionic liquids (vapour pressure very low),  $H_2O$ , many gases:  
at normal conditions, even for high pressures & shear rates, not for low temperatures
- laminar
- volume forces (gravity) neglected

### bearing geometry

- clearance slender
  - compared to typical macro-length (e.g. journal radius)
- perfectly hydrodynamic operation
  - 'hydraulically smooth' surfaces:  
macroscopic flow description unaffected by mean asperities

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# Outline

## Governing eqs in Eulerian representation

any **reference** frame  $\tilde{\mathbf{x}}, \tilde{t}$       $\tilde{D}_t := \partial_{\tilde{t}} + \tilde{\mathbf{u}} \cdot \tilde{\nabla}_{(\tilde{\mathbf{x}})}$

continuity

$$\tilde{D}_t \tilde{\rho} + \tilde{\rho} \tilde{\nabla} \cdot \tilde{\mathbf{u}} = 0$$

momentum

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thermal energy, 1st & 2nd law of thermodynamics

$$\tilde{\rho} \tilde{c}_p \tilde{D}_t \tilde{T} = \tilde{\beta} \tilde{T} \tilde{D}_t \tilde{\rho} + \tilde{\Phi} - \tilde{\nabla} \cdot \tilde{\mathbf{q}}, \quad \tilde{\Phi} = \tilde{\mathcal{A}} \cdot \tilde{\nabla} \tilde{\mathbf{u}} > 0$$

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Newtonian fluid      $\tilde{\mathcal{A}} = \underbrace{\eta}_{\text{shear}} [\tilde{\nabla} \tilde{\mathbf{u}} + (\tilde{\nabla} \tilde{\mathbf{u}})^T] + \underbrace{(\tilde{\eta} - \frac{2}{3}\eta)}_{\text{bulk viscosity}} (\tilde{\nabla} \cdot \tilde{\mathbf{u}}) \mathbf{I}$

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## Thermodynamic properties of 'simple' fluid

caloric eq of state

$$\tilde{h} = \tilde{h}(\tilde{p}, \tilde{T}) \quad \tilde{c}_p := \left( \frac{\partial \tilde{h}}{\partial \tilde{T}} \right)_{\tilde{p}} \left[ \frac{\text{J}}{\text{kg K}} \right], \quad \tilde{\beta} \tilde{T} = 1 - \tilde{p} \left( \frac{\partial \tilde{h}}{\partial \tilde{p}} \right)_{\tilde{T}}$$

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2nd law of thermodynamics

$$\tilde{\eta}, \tilde{\lambda}, \tilde{\beta}, \tilde{c}_p > 0, \quad \text{seldom } \tilde{\beta} < 0 \text{ (H}_2\text{O!)}$$

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## Thermodynamic properties of 'simple' fluid

caloric eq of state

$$\tilde{h} = \tilde{h}(\tilde{p}, \tilde{T}) \quad \tilde{c}_p := \left( \frac{\partial \tilde{h}}{\partial \tilde{T}} \right)_{\tilde{p}} \left[ \frac{\text{J}}{\text{kg K}} \right], \quad \tilde{\beta} \tilde{T} = 1 - \tilde{p} \left( \frac{\partial \tilde{h}}{\partial \tilde{p}} \right)_{\tilde{T}}$$

thermal eq of state

$$\tilde{\rho} = \tilde{\rho}(\tilde{p}, \tilde{T}) \quad \tilde{\beta} := - \frac{1}{\tilde{\rho}} \left( \frac{\partial \tilde{\rho}}{\partial \tilde{T}} \right)_{\tilde{p}} \left[ \frac{1}{\text{K}} \right]$$

$$\tilde{\eta} = \tilde{\eta}(\tilde{p}, \tilde{T}) \text{ [Pa s]}$$

$$\tilde{\lambda} = \tilde{\lambda}(\tilde{p}, \tilde{T}) \text{ [W/(m K)]}$$

2nd law of thermodynamics

$$\tilde{\eta}, \tilde{\lambda}, \tilde{\beta}, \tilde{c}_p > 0, \quad \text{seldom } \tilde{\beta} < 0 \text{ (H}_2\text{O!)}$$



# Outline

## Non-dimensional quantities

### kinematic quantities

$$t = \tilde{t}\tilde{U}/\tilde{L}, \quad \mathbf{x} = \tilde{\mathbf{x}}/\tilde{L}, \quad c = \tilde{c}/\tilde{C}, \quad \mathbf{u} = \tilde{\mathbf{u}}/\tilde{U}$$

### reference state

$$p = \tilde{p}/\tilde{p}_r, \quad \theta = (\tilde{T} - \tilde{T}_a)/\tilde{T}_r$$

$$\rho = \tilde{\rho}/\tilde{\rho}_r, \quad (\eta, \eta') = (\tilde{\eta}, \tilde{\eta}')/\tilde{\eta}_r, \quad \lambda = \tilde{\lambda}/\tilde{\lambda}_r, \quad \beta = \tilde{\beta}\tilde{T}_a, \quad c_p = \tilde{c}_p/\tilde{c}_{p,r}$$

### key groups

clearance slenderness  $\epsilon := \tilde{O}/\tilde{L}$

temperature ratio  $\beta = \tilde{\beta}\tilde{T}_a$

## Non-dimensional quantities

### Kinematic quantities

$$t = \tilde{t}\tilde{U}/\tilde{L}, \quad \mathbf{x} = \tilde{\mathbf{x}}/\tilde{L}, \quad c = \tilde{c}/\tilde{C}, \quad \mathbf{u} = \tilde{\mathbf{u}}/\tilde{U}$$

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$$\rho = \tilde{\rho}/\tilde{\rho}_r, \quad \theta = (\tilde{T} - \tilde{T}_a)/\tilde{T}_r$$

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### key groups

clearance slenderness  $\epsilon := \tilde{C}/\tilde{L}$

temperature ratio  $\gamma := \tilde{T}_r/\tilde{T}_a$

Rayleigh number  $Ra := \tilde{\rho}_r \tilde{U} \tilde{L} / (\tilde{\eta}_r \tilde{\beta} \tilde{T}_a)$

Prandtl number  $Pr := \tilde{\eta}_r \tilde{c}_{p,r} / (\tilde{\rho}_r \tilde{U} \tilde{L})$

Stokes number  $St := \tilde{\rho}_r \tilde{U} \tilde{L} / \tilde{\rho}_r \tilde{L}^2$

## Non-dimensional quantities

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### key groups

clearance slenderness  $\epsilon := \tilde{C}/\tilde{L}$

temperature ratio  $\gamma := \tilde{T}_r/\tilde{T}_a$

Reynolds number  $Re := \tilde{U}\tilde{L}\tilde{\rho}_r/\tilde{\eta}_r$

Prandtl number  $Pr := \tilde{c}_p\tilde{\eta}_r/\tilde{\lambda}_r$

Péclet number  $Pe := RePr$

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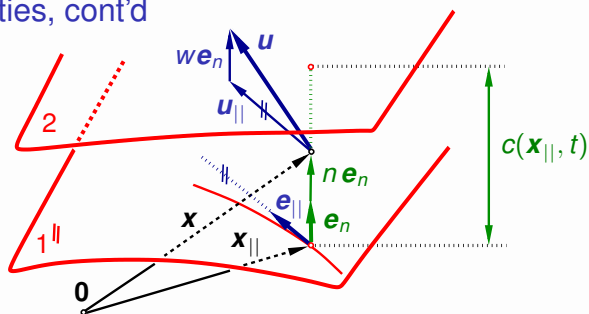
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### Non-dimensional quantities, cont'd



natural metric

$$\mathbf{x} = \mathbf{x}_{||} + \epsilon \mathbf{e}_n n, \quad \mathbf{u} = \mathbf{u}_{||} + \epsilon \mathbf{e}_n w, \quad \mathbf{u}_{||} = u_{||} \mathbf{e}_{||}$$

$$\mathbf{e}_{||} \cdot \mathbf{e}_n = 0, \quad \partial_n \mathbf{e}_{||} = \partial_n \mathbf{e}_n = \mathbf{0}$$

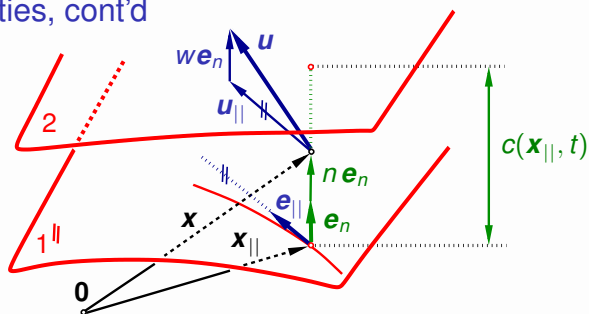
$$\nabla = \tilde{L} \tilde{\nabla} = \nabla_{||} + \epsilon^{-1} \mathbf{e}_n \partial_n$$

$$\nabla \cdot (\rho \mathbf{u}) = \nabla_{||} \cdot (\rho \mathbf{u}_{||}) + \underbrace{\mathbf{e}_n \cdot \partial_n (\rho \mathbf{u}_{||})}_{\mathbf{e}_n \cdot \mathbf{e}_{||} \partial_n (\rho u_{||}) = 0} + \underbrace{\epsilon \nabla_{||} \cdot (\rho \mathbf{e}_n w)}_{\rho w \nabla_{||} \cdot \mathbf{e}_n} + \underbrace{\mathbf{e}_n \cdot \partial_n (\rho \mathbf{e}_n w)}_{\partial_n (\rho w)}$$

$$D_t = (\tilde{L}/\tilde{U}) \tilde{D}_t = \partial_t + \mathbf{u} \cdot \nabla = u_{||} \cdot \nabla_{||} + w \partial_n$$



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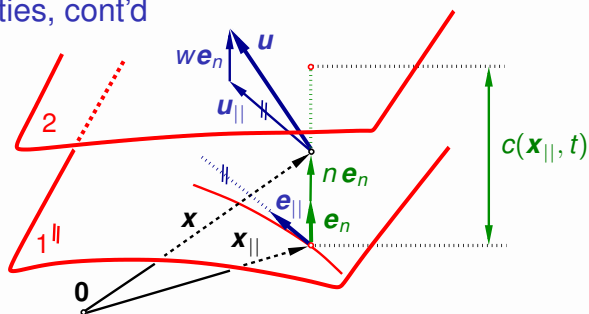
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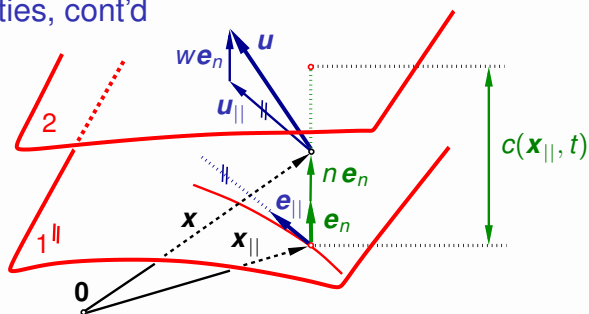
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## Navier–Stokes eqs

$$\tilde{p}_r := \tilde{\eta}_r \tilde{U} \tilde{L} / \tilde{C}^2, \quad \tilde{T}_r := \tilde{\eta}_r \tilde{U}^2 / \tilde{\lambda}_r$$

state	$q = q(p, 1 + \gamma\theta), \quad q = \rho, \eta, \lambda, c_p \Rightarrow \tilde{p}_r$
continuity	$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) \equiv \partial_t \rho + \nabla_{  } \cdot (\rho \mathbf{u}_{  }) + \epsilon \rho w \nabla_{  } \cdot \mathbf{e}_n + \partial_n (\rho w) = 0$
momentum	$Re \epsilon^2 \rho (\ddot{\mathbf{x}}_{ref} + 2\boldsymbol{\Omega}_{ref} \times \mathbf{u} + D_t \mathbf{u}) + \nabla p = \epsilon^2 \nabla \cdot \boldsymbol{\Delta}$ $\boldsymbol{\Delta} = \eta [\nabla \mathbf{u} + (\nabla \mathbf{u})^T] + (\eta' - \frac{2}{3}\eta)(\nabla \cdot \mathbf{u}) \mathbf{I}$
energy	$Pe \epsilon^2 \rho c_p D_t \theta = \beta(1 + \gamma\theta) D_t p + \epsilon^2 [\psi + \nabla \cdot (\lambda \nabla \theta)]$ $\psi = \boldsymbol{\Delta} \cdot \nabla \mathbf{u}, \quad \gamma := \tilde{T}_r / \tilde{T}_a$

$$\nabla \cdot \mathbf{u} \sim \epsilon^2 \nabla_{||} \cdot \mathbf{u}_{||}$$

$$\text{momentum} \quad \mathbf{0} \sim -\nabla_{||} p + \partial_n (\eta \partial_n \mathbf{u}_{||}), \quad \mathbf{0} \sim \epsilon^{-1} \partial_n p$$

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state	$\mathbf{q} = \mathbf{q}(p, 1 + \gamma\theta), \quad \mathbf{q} = \rho, \eta, \lambda, c_p \quad \Rightarrow \quad \tilde{\rho}_r$
continuity	$\partial_t \rho + \nabla \cdot (\rho \mathbf{u}) \equiv \partial_t \rho + \nabla_{  } \cdot (\rho \mathbf{u}_{  }) + \epsilon \rho w \nabla_{  } \cdot \mathbf{e}_n + \partial_n (\rho w) = 0$
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# Outline

## Limit process

classical lubrication approximation

thin film  $\epsilon \ll 1$

quasi-isothermal  $\gamma \ll 1$

inertia neglected  $Re \epsilon^2 \ll 1$ , laminar flow:  $Re \lesssim 10^5$

typical values  $\epsilon \lesssim 10^{-3}$ ,  $Pr_{oil} \approx \frac{70 \dots 10^3}{100 \dots 20^\circ C} \Rightarrow Pe \lesssim 10^8$ ,  $Pe \epsilon^2 \lesssim 10^2!$

$$\nabla \cdot (\rho \mathbf{u}) \sim \nabla_{||} \cdot (\rho \mathbf{u}_{||}) + \partial_n(\rho w) + O(\epsilon)$$

$$\rho(\rho, 1 + \gamma \theta) \sim \rho(\rho, 1) + O(\gamma)$$

expansions

$$\nabla_{||} \sim \nabla_{||}^0 + O(\epsilon) \quad \nabla_{||}^0 = \nabla_{||} \quad \text{for } n=0$$

$$[\mathbf{u}_{||}, w, \rho, \theta, \eta, \dots](\mathbf{x}_{||}, n, t; \epsilon, Re, \gamma, \dots) \sim [\mathbf{U}, W, P, Q, \Theta, \mathcal{N}](\mathbf{x}_{||}, n, t) + \dots$$

$$c \sim C(\mathbf{x}_{||}, t) + O(\epsilon) \quad \text{journal bearing!}$$

## Limit process

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$$\nabla \cdot (\rho \mathbf{u}) \sim \nabla_{||} \cdot (\rho \mathbf{u}_{||}) + \partial_n (\rho w) + O(\epsilon)$$

$$\rho(p, 1 + \gamma \theta) \sim \rho(p, 1) + O(\gamma)$$

### expansions

$$\nabla_{||} \sim \nabla_{||}^0 + O(\epsilon) \quad \nabla_{||}^0 = \nabla_{||} \quad \text{for } n = 0$$

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$$\nabla \cdot (\rho \mathbf{u}) \sim \nabla_{||} \cdot (\rho \mathbf{u}_{||}) + \partial_n (\rho w) + O(\epsilon)$$

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### expansions

$$\nabla_{||} \sim \nabla_{||}^0 + O(\epsilon) \quad \nabla_{||}^0 = \nabla_{||} \quad \text{for } n = 0$$

$$[\mathbf{u}_{||}, w, p, \rho, \theta, \eta, \dots](\mathbf{x}_{||}, n, t; \epsilon, Re, \gamma, \dots) \sim [\mathbf{U}, W, P, Q, \Theta, \mathcal{N}](\mathbf{x}_{||}, n, t) + \dots$$

$$c \sim C(\mathbf{x}_{||}, t) + O(\epsilon) \quad \text{journal bearing!}$$

## Limit process

### classical lubrication approximation

thin film  $\epsilon \ll 1$   
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## Leading-order eqs

state & energy  $Q = Q(P, \mathbf{1})$ ,  $Q = Q$ ,  $\mathcal{N}$

continuity  $\partial_t Q + \nabla_{||}^0 \cdot (Q \mathbf{U}) + \partial_N(QW) = 0$  (1)

momentum  $\nabla_{||}^0 P = \partial_n(\mathcal{N} \partial_n \mathbf{U})$ ,  $\partial_n P = 0 \Rightarrow \partial_n Q = \partial_n \mathcal{N} = 0$  (2)

kinematic BCs

$n = 0$ :  $\mathbf{U} = \mathbf{U}_1(x_{||}, t)$ ,  $W = W_{p,1}(x_{||}, t)$  (3)

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(1), (3), (4)  $\Rightarrow \partial_t(QC) + \nabla_{||}^0 \cdot \left( Q \int_0^C \mathbf{U} dn \right) + Q(W_{p,2} - W_{p,1}) = 0$

(2), (3), (4)  $\Rightarrow \mathbf{U} = \underbrace{\frac{\nabla_{||}^0 P}{2\mathcal{N}(P)} n(n-C)}_{\text{Hagen-Poiseuille}} + \underbrace{\frac{n}{C}(\mathbf{U}_2 - \mathbf{U}_1)}_{\text{Couette}}$



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## Integral mass balance

$$\int_0^C \mathbf{U} dn = \mathbf{Q} + C \mathbf{U}_m, \quad \mathbf{Q} := -\frac{C^3 \nabla_{||}^0 P}{12 \mathcal{N}}, \quad \mathbf{U}_m := \frac{\mathbf{U}_1 + \mathbf{U}_2}{2}$$

generalised Reynolds eq O. Reynolds (1886), A. Sommerfeld (1904), L. Prandtl (1937)

$$\nabla_{||}^0 \cdot (-Q \mathbf{Q}) = \underbrace{\left( \partial_t + \mathbf{U}_m \cdot \nabla_{||}^0 \right)}_{\text{'squeeze' Couette + sliding = 'wedge'}} (QC) + QC \nabla_{||}^0 \cdot \mathbf{U}_m + Q \underbrace{(W_{p,2} - W_{p,1})}_{\text{permeability}}$$

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elliptic 2nd-order PDE for  $P(\mathbf{x}_{||}, t)$  and given  $C(\mathbf{x}_{||}, t)$ ,  $\mathbf{U}_m(\mathbf{x}_{||}, t)$

kinematic wave operator  $\partial_t + \mathbf{U}_m \cdot \nabla_{||}^0$  most relevant for gas bearings

linear for incompressible lubricant with constant properties ( $Q \equiv \mathcal{N} \equiv 1$ )

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## generalised Reynolds eq — some important properties

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rigid contacts, no Navier slip  $\nabla_{||}^0 \cdot [\mathbf{U}_1, \mathbf{U}_2, \mathbf{U}_m] = 0$

Galilean transformation  $[\mathbf{x}_{||}, t] = [\mathbf{x}'_{||} + \mathbf{S}(t'), t']$

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## Validation of tribo-systems

typically find

- $P(\mathbf{x}_{||}, t)$ ,  $\mathbf{x}_{||} \in \Omega$  subject to  $P(\partial\Omega, t) = P_a$

- load-bearing capacity  $\mathbf{F}(t) = \int_{\Omega} P \mathbf{e}_n d\Omega$

clearance  $C(\mathbf{x}_{||}, t)$  is

- prescribed

- spring from pad-clamping mechanism

- mechanical link with spring  $\rightarrow P = P_0 + P_1 C + P_2 C^2$

- $P_0, P_1, P_2 > 0$

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machinery (e.g. shaft) dynamics  $\rightarrow P = P(\Omega, C, \dot{\Omega}, \dot{C}, \ddot{C})$   
EHL  $\rightarrow P = P(C)$

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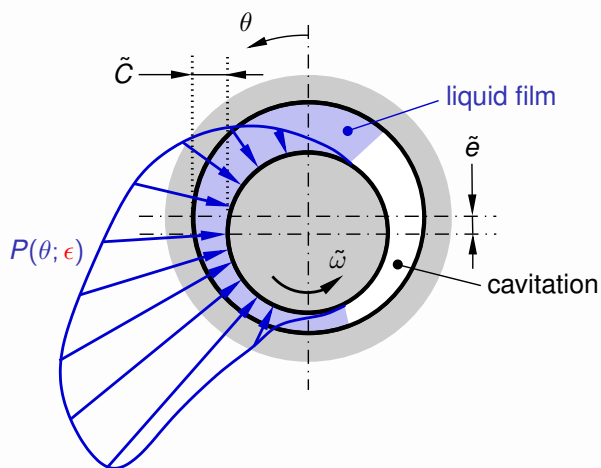
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Classical application: journal bearing



- reference quantities  $\tilde{U}_m = \tilde{\omega} \tilde{R}_i, \quad \tilde{p}_r = \tilde{\eta}_r \tilde{\omega} \tilde{R}_i^2 / \tilde{C}^2$
- geometrical parameters  $\epsilon = \tilde{C} / \tilde{R}_i \ll 1, \quad \text{eccentricity } \epsilon = \tilde{e} / (\tilde{R}_a - \tilde{R}_i)$
- non-dimensional quantities  $C = 1 + \epsilon \cos \theta + O(\epsilon^2), \quad U_m (= \mathcal{N} = \mathcal{Q}) = 1$

## Further outlook

### include

- EHL
- inertia ( $Re\epsilon^2 \sim 1$ , start-up, high-speed rotors, rapid load cycles)
- turbulence
- film rupture & cavitation (surface tension)
- effects acting on micro-scale  $\ll \epsilon$  (surface roughness, mixed friction)

### rational method: perturbation techniques

- multiple scales, matched asymptotic expansions
- numerical solution of reduced problem (simulation tools)



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Thank you for your attention !