Palladian Graphs

Using a graph grammar to automate the Palladian grammar

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Abstract. An implementation of the Palladian grammar using a graph grammar and a graph to shape mapping is presented. The application is embedded in a parametric CAD environment and allows the exploration of Palladian villas by hand or by using a random generator.

Keywords. Grammar; graph; shape; implementation; automation.

Introduction

Graphs and graph grammars are well known as tools to explore abstract systems of objects and their relations. In architecture these are often interpreted to be programmatic functions and their interrelations or, more concrete, spaces and their adjacencies (Steadman, 1976). This project attempts to show that shape bound considerations can also be addressed using graphs if they are modelled appropriately and a graph to shape mapping can be established.

Palladian Villas have consistently been used to introduce new ideas for shape grammars; here too they serve as proof of concept. The rules taken from Stiny and Mitchell (1978) are transcribed into their graph equivalent. The graph grammar is executed and the result is transformed into a plan by an interpreter module.

The implementation was to create a prototypical workflow to be used for numerous grammar implementations. Furthermore the logic was to be embedded into an existing CAD environment in order to reduce the necessary work of designing and interface and enabling the user to modify the results in a familiar environment.

Implementation

The graph grammar was modelled in GrGen.NET, this graph rewriting system allows the graph model and the rules to be described in tailor-made modelling languages and to compile the grammar into more efficient.NET assemblies. These assemblies can then be included in any programming project that supports.NET. There are numerous CAD packages which support plug-ins developed in this manner; this project is implemented as Add-In for Autodesk Revit.

Grammar

There are several approaches to graph grammars, depending on what kind of object is being rewritten and how elements are mapped from the left hand side of a rule to the right hand side. The single pushout approach (SPO), which enables unrestricted grammars, is used for this implementation (Rozenberg, 1997).

Graph grammars have been used extensively in numerous fields from pattern recognition to developmental biology; hence the methodological toolset is comprehensive. Four our purpose it is important
to grasp the concepts of preservation morphism and negative application conditions (NACs). The preservation morphism describes the method of mapping nodes and edges from the left side of the rule to the right. Shape grammars use a coordinate cross and Euclidean relations to achieve the same but Euclidean relations do not apply to graphs, hence another method for describing how the changes take effect had to be devised. NACs allow the definition of features which may not be part of the graph in order to achieve a match.

The grammar is based on the Palladian grammar by Stiny and Mitchell (1978). That is, each shape grammar rule was taken and the graph grammar equivalent was implemented. Sometimes the nature of graph grammars enabled several shape rules to be represented as one, other times additional rules are required.

The basic sequence is to construct an adjacency graph for the \((2m + 1) \times n\) grid underlying the design. Collapse nodes to achieve the different layouts, thereby keeping all the edges except if they turn into loops. This has twofold implications. First, we are dealing with a multi-graph, since two nodes may be connected by several edges. Second, an edge represents an actual wall segment and not merely the fact that two spaces are adjacent, this knowledge can be but to use during the transformation process. Subsequently exterior spaces such as the porticos are added and the edges are modified to represent features such as realignments, doors and windows.

In practice it has proven helpful to add some additional nodes to the procedure described above. The entire structure is bound by orientation nodes representing north, east, south and west, much as described by Steadman (1976). A state node is used to help guide the grammar through the various phases of creation. This corresponds to the label on the central axis in the Palladian grammar. Finally a star formation sub-graph was introduced to hold parameters such as the dimensions of the underlying grid.

It must also be noted that the nodes and edges of the graph can be of different types and each can hold several attributes. In visual representations this is shown with various decorations and labels respectively (Figure 1). The hierarchy of node types is shown in Figure 1a. During the sub-graph matching process a node can be mapped to any node of its own type or of a descendant type. The status, parameter and orientation types hold attributes for the grammars status, a name-value pair and a direction respectively.

The edges, which are all undirected, are either of the North-South type or of the East-West type (Figure 1b). All edges hold the same attributes: an integer value holding an axis identification number, boolean values for features such as doors or windows and some floating point values used for wall realignment.

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![Diagram](image_url)
The conventions used to depict the graph grammar rules are shown in Figure 1c. The most important concept for understanding the rules is the marking of nodes. If a node is shown as marked within a rule, this does not mean that the node is also marked in the graph. This is contradictory to what one would expect from the labels of a shape grammar. Markings are used only to map nodes from the left hand side of the rule to the right hand side. In this sense they are more like the coordinate cross in shape grammars than labels. This convention is the visual representation of the preservation morphism explained above.

If nodes are concatenated, their marks are also concatenated. Edges attached to only one of the source nodes are transferred to the newly created combined node, edges attached to both are deleted. Labelled nodes are used to depict specific orientation nodes. The letters \( \{N, E, S, W\} \) are not mere markings, they represent specific direction attributes.

Edge attributes are written next to the respective edge symbol as a name-value pair. If there is no name, a lowercase string from the set \( \{wa, c, d, wi, o, e\} \), indicating which attribute is being referred to (Figure 1b), the axis identification number is used by default.

The rules are numbered, for easier reference the numbers of the respective rules in the Palladian grammar are given in square brackets.

The initial graph is simply a status node set to \textit{Initial} (Figure 2). The first rule which marks the beginning of the grid generation, adds the parameter root and a rudimentary adjacency graph consisting of one centre room node and the four orientation nodes. Note that for convenience the two edges connecting each pair of orientation nodes are shown as one with...
two symbols throughout the following depictions.

While the whole grammar cannot be shown here due to space restrictions, the initial graph and the first rule are shown in Figure 2, the rule set for the generation of the grid is shown in Figure 3 and the rule set for the concatenation of spaces is shown in Figure 4.

**Villa Malcontenta**

Figure 5 shows an example derivation of the graph for the Villa Malcontenta. The attributes of state and orientation nodes are shown throughout the sequence in order to facilitate understanding. Edge attributes are shown only if they have been modified by the preceding step.

**Transformation**

Although the generated graph does not hold a whole lot of information, due to additional knowledge about Palladio’s Villa designs it is possible to generate the floor plans. The orthogonal nature of the designs, the reduced formal vocabulary, the dominance of the underlying grid and the uniform placement of doors and window along an axis all provide information to transform the graph into a plan.

Essentially each edge is transformed into a wall segment including optional features such as windows and doors, part of a colonnade or a void. First the transformation must determine orientation and position of the segment. The object type for replacement is then determined by looking at the nodes connected by the edge.
The orientation of the wall is determined by the edge type. The position of the wall segment can be determined by looking at the axis identification number of the edge and its neighbouring edges. Essentially each node covers a certain range of axes in each direction. Information about the actual form of the space is not carried directly in the graph and must be derived by looking at each edge in detail. Thus the three cases shown in Figure 10 have to be taken into consideration and can be resolved based on the fact that there can be only one non-rectangular space, which must contain the central axis.

The base case (Figure 6a) shows two adjacent spaces, it is clear that the wall’s position must be in between the two.

Should the ranges of the spaces overlap, they
must also bypass each other to some extent. If one space encloses the other as shown in Figure 6b, it is clear that it cannot be rectangular, thus the other one must be and the wall can be placed at its boundary.

Alternatively, the spaces might overlap on a corner (Figure 6c). In order to resolve this case it must be determined which space contains the central axis and thus is the non-rectangular space. Again the wall can then be placed along the other spaces boundary.

This determines between which axes the wall is, its position **within the coordinate system is then calculated** using the parameters and optional offsets.

Once the position is determined the objects can be generated according to the edges attributes (Figure 7) and its nodes. Thereby it is important to notice that replacement rules are ordered from the specific to the general and edges must be replaced by applying the first matching rule. Door sizes are for example chosen according to the kind of spaces they connect. Doors leading from the interior to the exterior are larger (3) than internal doors (4) and doors leading from a portico to the exterior (5, 6) are interpreted to be arches. The exact position the opening within the wall segment can be determined by a parameter, if nothing is set a default value is used.

This step is greatly facilitated by modern object-orientated CAD environments. Objects such as walls, windows and doors can be modelled in advance to any chosen level of detail; the transformation process must then simply generate instances from the given libraries and compose them appropriately.

<table>
<thead>
<tr>
<th>1</th>
<th>wa:1 d:1 wi:1</th>
<th>2</th>
<th>wa:1 wi:1</th>
<th>3</th>
<th>wa:1 d:1</th>
<th>4</th>
<th>wa:1 d:1</th>
<th>5</th>
<th>wa:1 d:1</th>
</tr>
</thead>
</table>

Figure 6
Possible cases the transformations must consider. The arrow marks the position where the wall segment will be placed.

Figure 7
The attribute sieve determining the edge transformation. Edges are replaced by the first match.
Shape grammar

Once the wall segments have been positioned and sized on the plan, the wall joins need to resolved in order to receive a clean plan. The rules in Figure 8 show the possible configurations and their resolution. The rules must be applied in the shown order; every rule must be applied as often as possible before stepping to the next rule.

Since we are dealing with orthogonal joins of monolithic walls this step shows little complexity. The shape grammar part could be more powerful, but it was not deemed necessary here.

Derivations

Some results of the Palladian transformations are shown in Figure 9. The Villa Foscari and the Villa Badoero from Palladios body of work and the Villa Hollywood generated by Stiny and Mitchell.

Interface

The rules are implemented as buttons in the user interface, after each application of a rule the model is updated to reflect the changes. Additionally the
environments allows for two features beneficial to usability. First each rule can be assigned a detailed tooltip description; this is used to explain what effect the rule will have and to compare the respective shape grammar rule to the graph grammar rule. Second the activity state of each button can be set individually; this means if a rule cannot be applied because the derivation is currently in the wrong state or the current configuration simply does not allow its application the respective button can be set inactive. This is implemented by a group of test rules, which can be applied to the graph and which return a boolean value, indicating if a set of conditions is met or not.

**Random Generation**

Apart from being able to apply the rules manually one-by-one, a random generator was implemented to generate derivations at the push of a button. The application of rules is guided by weighted random numbers in order to increase the probability of an appealing result.

**Conclusion**

Overall it is an interesting exercise to translate a shape grammar into its graph equivalent. Of course it would be sensible to model rules that are more accessible to a graph approach if this methodology is used for new grammars. This would mean concentrating on functional considerations and adjacencies rather than on purely formal arrangements of spaces. These Palladian piano nobiles do not lend themselves well to this approach and hence can be seen as an extreme example, well suited for testing.

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**Figure 10**
A montage showing the ribbon of the Autodesk Revit Add-In and several steps of a derivation.

**Figure 11**
Four randomly generated plans.
However, future projects will inspect this line of thought.

It was shown that the information contained and transformed by a shape grammar can be abstracted into a graph grammar to enable easier computation. The final graph can then be transformed back into a visual representation. Intelligent transformation mechanisms can conceal implementation details from the end user if desired. This will most likely require transformations after each rule application either by updating the changes or simply by recalculating the entire structure.

Acknowledgement

The graph grammar was implemented with GrGen. NET (Geiß et al., 2006). The resulting libraries were embedded into an Autodesk Revit Add-In, which is also used for the topomorphical transformation; the final cleaning up of the plan was actually left to the wall join functions built into Revit. The shape grammar equivalent is included here for the sake of completeness. The Add-In is available from the authors.

References
