ABSTRACT

Hospital simulation has so-far concentrated on late phases of architectural planning, in which the design is already fully formulated and undergoes optimization. This paper moves into the exactly opposite direction - it tries to embed simulation into the earliest phase imaginable, which, interestingly, is well before any architectural planning occurs: The pre-tender work that is done by or on behalf of the client, using naïve diagrams based on interviews with the medical staff as models.

Keywords: early design process, hospital planning, diagrammatic tools, pre-tender simulation

1. INTRODUCTION

The preparation of a tender represents the earliest work done in hospital planning: Projected medical demands of a care region are mapped to either the establishment of a new hospital, or, more often, to an extension, adaptation or refurbishment of an existing one. Classically, the tool of choice for 'simulating' and 'calculating with' future demands has been spreadsheet software. Apart from statistical data, diagrammatic information (e.g. envisioned work processes and spatial arrangement of departments, obtained by interviewing the medical staff) is also generated. However, and in contrast to spreadsheets, there is a great lack of methods for interacting with the so-encoded data - especially when it comes to animation/simulation of (patient and material) flow.

Contribution: During the past half year, we have thus been working on reverse-engineering diagrammatic representations into simulation models, dealing with needs-orientated flow descriptions (patient flow), preliminary floor plans (schemata) and functional decompositions (bubble diagrams), in order to obtain a simulation targeted at the pre-tendering phase. To discuss the techniques used in this context and give a wider perspective on other possible applications is the main topic of this paper (see Section 4, “Contribution Details”).

Establishing simulation in the earliest phase of planning enables clients to get a better overview of the project they are writing a tender for. Furthermore, diagrammatic data produced as result of the subsequent competition phase can thus be evaluated and compared, which is advantageous for a wide audience:

- Planners. The spatially simulated flows can inform the design and enable a cross-check of requirements for the planned building. Generally, the flow given by the client represents a preliminary concept (“schema”), in which the spaces are not fully formulated. However, the processes depicted therein stay essentially the same, even after the architect has designed the final form (“floor plan”). By adaptation of the schema into the final floor plan, the architect can simulate the flow in his presented concept, while still relating to the client’s vision.

- Staff. The hospital staff can be trained using the very same simulation, in which context also an acceptance check can take place. As the initial flow concept is typically generated by the same persons that will see the simulated final design, this enables to re-use the previous knowledge for evaluation.

- Client. Verification of requirements, as mentioned, can help in the decision process during the competition phase. Moreover, as the hospital goes into operation, realtime data concerning the actual patient flows can be exported from the Enterprise Resource Planning (ERP) system, in order to input and visualize these in the sense of a “management dashboard”. To some extent, this also facilitates a verification of the building’s operational concept.

2. RELATED WORK

Diagrams (White 1986; Seonwook and Miyoung 2012) are used as representations for the envisioned organization, i.e. space allocation (zones and their adjacency relations, circulation), hierarchy and responsibilities (organizational chart), temporal or causal order (processes, flow). The sources for this information vary; however, one common point is that planning is never done in isolation, but by drawing on pre-existing knowledge of several health professionals, such as physicians, nurses and therapists, administrative personnel and (most importantly) the patients
themselves. Tool support for employing diagrams as interview technique, used to let workshop participants record daily work routines in a game-like manner, was presented by (Wurzer, Fioravanti, Loffreda and Trento 2010). Simulation in the same setting, as “assessment tool”, has so far not been conducted. What exists in early-stage spatial simulation are approaches exploring space utilization (Tabak 2008; De Vries, Jessurun and Dijkstra 2002), verification of a functional program (Wurzer 2010), usage simulation and pathway visualization (Wurzer 2011) and early process simulation (Wurzer 2012).

3. BACKGROUND
As stated earlier, work that leads to the definition of early diagrams (most importantly: the architectural schema) is conducted collaboratively between health professionals and patients. The overall goal is to define requirements that enable effective workflows according to customer needs and expectancies. Because objectivity during such an elaboration process is of vital importance, work typically proceeds in workshops targeted at a specific problem domain.

Outputs are at first centered on process knowledge - i.e. daily work routines, clinical procedures and practices, such that one might produce business processes for outpatient, inpatient and day hospital treatment, according to the different areas of the hospital as defined in (DIN 13080 2003) as result. One may also specify procedures in case of special situations - e.g. mass accidents, which is especially important for trauma clinics. With these processes in mind, one may look at the intended spatial configuration, which is the topic we are focusing on in our work. In more detail, we employ three specific types of diagrams produced within pre-planning:

1. The architectural schema (see Figure 1a) as a hierarchy of “spaces within spaces”. A space is a bounded (usually rectangular) region that is denoted by a name. It contains a set of functions, i.e. names of activities that may be used in that space. Each function is a resource of limited capacity, of which the usage is computed during the subsequent simulation (see Simulation). It is crucial to note that the schema is fundamentally different from a floor plan showing the form of each space: It rather gives the approximate area and location of each space in two-dimensional arrangement, which is then detailed into the fully-formulated three-dimensional building layout during the competition.

2. Flows (see Figure 1b) depicted as arrows on top of the schema, giving a simple yet effective way to express paths of building users (Lohfert 2005). Usually, these are color-coded to distinguish different kinds of traffic (patients, staff, visitors).

Figure 1: (a) Architectonical schema as arrangement of nested spaces with functions. (b) Superimposed flows.

3. Bubble diagrams depicting the adjacency relations between functions in a purely abstract manner; a function is visualized as circle (“bubble”), the adjacency relation to another function as connecting line. Adjacency can either be “close” (denoted e.g. by a green line) or “separate” (denoted e.g. by a red line), “not given” or “not applicable” (no line or gray line). Additionally, it is common to depict this relation also by arranging close functions into clusters.

Figure 2: Bubbles diagram showing bubbles (representing functions). The size of a bubble corresponds to its assumed area consumption, the relationships between functions are given as colour-coded lines.

When using diagrams as source of information, one can exploit hidden semantics given by the topology of shapes present, in order to infer semantic relationships. More specifically (refer to Figure 3):

- Nesting of spaces (Figure 3a) can be inferred from topological inclusion.
- Conceptual containment (Figure 3b), in contrast to ‘real’ nesting, hints at a grouping of spaces using an abstract boundary, signified by a dashed line.
- Using and being used by (Figure 3c) according to the z-order - the lower element is using the higher one, transitively.
4. CONTRIBUTION DETAILS

Our work first derives a spatial model from a schema (see “Rectangle analysis”, 4.1). The result is a semantically rich model of a hierarchy of spaces, together with the functions they contain. This is then used in the second phase, where patient flow is computed using an Agent-Based Simulation (ABM) that computes the progression of patients through the spaces, utilizing a sequence of functions as resources. Arrivals of patients are given as spreadsheets, based on either (hypothetical) arrival times and functional sequences, or, more commonly, using real data obtained through either the Hospital Information System (HIS) or the underlying Enterprise Resource Planning (ERP) System. As functions are the resources within the simulation, their usage is recorded and visualized in the third phase as Bubble diagram: For each function, a bubble with circle size according to capacity is drawn. The circle is colored according to functional utilization compared with capacity (under-utilized, over-utilized or well-utilized). Relationship lines between function are also depicted, based on the simulated flow between functions. Conceptually, this work is similar to e.g. (De Vries, Jessurun and Dijkstra 2002) - being a design and decision support tool based on employing simulation in the architectural workflow. Our focus on earliest stages (i.e. pre-tender phase) is, however, unprecedented in hospital planning, requiring careful though over what data already exists, as will be shown in the following elaborations.

4.1. Rectangle analysis

Schema diagrams are drawn intuitively, as rectangles-within-rectangles and possible overlaps. In this section, a quick run-through of the analyzed features is made (also refer to Fig. 4):

- **Hierarchy buildup.** The pair-wise analysis of topological relationship between each two rectangles gives either “separated”, “completely included in/completely including”, “intersecting” or “touching”. In the first (trivial) case, the rectangles are completely separate and thus modeled as own entities. In the second case “included in/including”, the rectangles form a parent-child relationship. When “intersecting”, the rectangles also form a parent-child relationship; however, it is still unclear which is the parent and which the child rectangle. Z-order of the rectangles can be used as tie-breaking mechanism - the child element being the one that is arranged ‘on top’. Intersections are commonly used spaces that are used by more than one parent - e.g. a central operation theatre being used by many connecting areas. Accordingly, the hierarchy we build up offers, for each rectangle, the ability to have more than one parent - thus forming a semi-lattice rather than a tree structure (Alexander 1965). The last case, “touching” rectangles, is ignored - we assume each of the both rectangles are children of a common parent structure, and the touching relation being there to depict adjacency, not hierarchy.

![Figure 3: Hidden logic in Diagrams](image)

- **Subordinate space usage** (Figure 3d, space B is using A and C) and sharing (Figure 3e, B shared between A and B).
- **Sharing** can also be seen for functions (Figure 3f), however, the opposite case (function using two spaces) is not possible: Functions are always subordinate to spaces.

The actual use of these properties is presented in Section 4.1 “Rectangle analysis”.

![Figure 4: Depiction of the first part of the workflow](image)
• **Space and function attribution.** Up to this point, it is not clear whether the analyzed rectangles stand for spaces or functions, since both are nested rectangular elements. By use of manual attribution, we can infer that a given rectangle represents the latter structure - in which case it must also contain a capacity (integer). Additionally, in order to facilitate the later use of the function as resource, we also allocate a list currently occupying and queued agents.

4.2. **Flow Simulation**

Flow is given by arrivals in spreadsheet format, where each line represents one single patient (see Figure 4). Also on this line are 1.) the arrival time and 2.) the sequence of functions to visit, including stay time per function. Then, the simulation scheduler progresses in discrete time steps, in which:

1. **Arrivals** for the current instance are instantiated, producing agents with a fixed protocol of functions to visit. The first of these functions is immediately removed from the list, and the agent location is set to the space containing the function.
2. **Movement** of agents is simulated for all agents that are crossing to the next function. This happens with reference to the underlying schema, which is interpreted as circulative network.
3. **Occupation** of functions is simulated by employing the active and queue lists of the function under consideration; the total time spent per function is available in the agent itself, reflecting the amount of time taken for individual treatment. Simulation constructs such as passivation/activation can happen in this step, or, trivially, the agent waits for that time-span.
4. **Goal selection** happens for those agents that have finished using their function, by removing again the first element of the list of functions still to be visited. In case there is no such function, the agent is removed from the simulation.

The simulation runs as long as there are elements in the arrival list or there are active agents on the schema. In case the simulation ends, the visualization is prepared.

4.3. **Visualization**

In architectural workflow, Bubble diagrams are used to depict relations among functions; however, these are only intended relationships (i.e. intended by the architect, from close collaboration to dislocated). In our simulation, the results are used to build up such a diagram, based on the actual usage of functions and flows between them (also refer to Fig. 5a). For each function (depicted as a circle), we depict the usage as its radius, the interpretation of this usage compared with the capacity as color (under-utilized=blue, over-utilized=red, well-utilized=green, not enough data=gray). The flows between functions hint at their level of cooperation. By thresholding, we can get a measure of closely cooperating function pairs, depicted as lines. However, in contrast to Bubble diagrams that have been specified manually, we cannot state which functions should not cooperate at all, and should thus be dislocated (e.g. for means of privacy, hygienic aspects, etc.) - our approach is inherently positivistic in this aspect. The resulting Bubble diagram can nevertheless be compared to a manually-made one, as validation.

As visualization, we can record the usage of functions over time (see Figure 5).

**Figure 5:** (a) Visualization of functional relationships obtained by using the flow simulation. Circles depict functions, links between them cooperation in the (simulated) work process. The size of each circle corresponds to the usage of the given function, the color is a comparison between usage and capacity (green: well utilized, red: over-utilized, blue: under-utilized, gray: too little data). (b) Depiction of usage of each function (red line indicates the capacity having been set by manual attribution).

5. **DISCUSSION AND RESULTS**

The stated approach was implemented and tested with anonymized patient trails (inpatients and outpatients, 1900 individuals) exported from a hospital’s ERP system (SAP) and OT management system (60 individuals) for the course of one day which we see as being quite average - a Wednesday in non-vacation time. Technically, we received a sequence of time-stamps together with the service point (e.g. 10:05 Radiology, 11:39 Pediatrics) for each anonymized patient. From this, we could build a trail “Radiology > Pediatrics” and inferred durations from the time delta. The resulting duration is, arguably, not correct - but it is not wrong either:

• **Shortcoming 1.** The given timestamps are recorded either at the start or at the end of the service duration, which is bad. But, even worse than that, we can safely assume that both cases are present in the same dataset (e.g. OT times measured at start, radiology at the end of the service duration). Thus, the data is necessarily fuzzy, and must not be interpreted...
quantitatively but rather qualitatively and with a grain of salt.

- **Shortcoming 2.** We cannot compute durations from a single time stamp (or, as in the example mentioned earlier, we do not know how long the patient was in the Pediatrics unit). To counter this problem, average service times were used where available.

- **Shortcoming 3.** The duration computed has not necessarily got to do anything with the real service time. For example, the time delta between 11:39 Pediatrics and 10:05 Radiology would be 1 hour 34 minutes, which is a rather long time for, say, an x-ray. Again using average service times (e.g. x-ray: 4 minutes), one can dispatch the patient to the next function and use the remaining time as waiting time (i.e. Radiology(4m)>Pediatrics(1h 30m)).

In contrast to the mentioned problems, we also saw a large benefit: We were able to transfer knowledge about a hospital to a new design, using arrivals and current trails as input for a new design. For this to be possible, a transformation and mapping step was incorporated into the interpretation of the timestamps: Each current service point name was replaced by the name of the future planned function (e.g. ‘Pediatrics’ becomes ‘Pediatric Centre’). In the same instance, we also distinguished trails by the type of patient (inpatient/outpatient) and functions present in the trail, in order to colour-code them (see Figure 6a). In this fashion, an outpatient with the trail Radiology(4m)>Pediatric Centre(1h 30m) would be tagged as child. By the assumed type of person, we also choose an entrance space to complete the arrival, i.e. arrival at 10:05: Main Entrance(0m) > Radiology(4m) > Pediatric Centre(1h 30m) > Main Entrance(0m). The passage times between functions are disregarded.

Figure 6: Implementation in Microsoft Visio. (a) Graph editor used for inputting schema and, subsequently, for depicting the flow of agents across a set of functions, which is visualized as bubble-diagram. (b) Manual attribution of shapes and setting of capacity for functions. (c) Depiction of function usage over time.

Figure 7: Screens used for the simulation. (a) Main screen with choice of spreadsheet and buttons to start rectangle analysis, reset simulation, run simulation, scale bubbles and compute usage. (b) Scale bubbles screen, giving the choice to scale usage (bubbles) and throughput (relations).

6. IMPLEMENTATION DETAILS

Our implementation uses Microsoft Visio for graph drawing (see Figure 6a). Under the hood, we are employing the bundled Visual Basic for Applications scripting language as means for enabling simulation, i.e. topology analysis and animation/simulation. The former point deserves some more detail: Visio is an excellent tool for doing topological analysis; it comes with a built-in support for finding the spatial relation between pairs of shapes, resulting in either containing, contained in, overlapping, touching or none. Likewise, the support for animation and automated diagram drawing (which we needed for the bubbles) is excellent, and lead to a total development time of less than a month. Also, the possibility for attribution of shapes via shape data (see Figure 6b) proved a valuable tool with which the users were already acquainted. Likewise, the ability to define custom shapes made it possible to put usage monitors (see Figure 6c) into a palette, with users being able to drag them onto the drawing sheet and anchor them to the function to be monitored.

Deployment of the simulation is also fairly easy - the user needs to open a diagram containing the scripts in parallel to the diagram to be simulated. By this, we are able to reach a wide audience that is not tech-savvy, or even (one might say) reluctant to install additional simulation software. For the end-user, the simulation is invoked via an additional menu of Microsoft Visio, which brings up the user interface (refer to Figure 7):

- In the main screen (Figure 7a), the user selects an arrival spreadsheet and can then start the rectangle analysis and simulation.
- During the simulation, the user can scale bubbles and relations (see dialog in Figure 7b). The usage is computed in regular intervals,
which the user can override by pressing a “compute usage” button.

CONCLUSIONS
We have presented a novel approach that helps clients simulate a very preliminary schematic diagram, targeted at the pre-tender phases of a hospital project, where requirements have to be elaborated in close collaboration between medical staff and patients. The output of the approach is suitable as input for the competition, since it speaks the language architects understand (i.e. bubble diagrams, functions and spaces).

REFERENCES

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